OCTOPUS VACUUM GRIPPING

SYSTEM QUESTIONNAIRE				Company					
Sy:	r a correct dimensioning of a stem, it is important to know ad to be handled.	ne	Address						
	r this reason, please fill out the ck to us via e-mail or fax.	the following form and send it		Post code / City	1	Country			
We	e will suggest the best Octop								
WC	ould allow us to offer the best			Contact person:					
	mail: tecnico@vuototecnica.r x: + 39 039 5320015	net		Telephone		Fax			
				E-mail					
1)	In which industrial sector v	would the Octopus be used?							
	□ Plastic	□ Wood		☐ Glass/Sol	ar	☐ Steel sheet			
	☐ Marble/Stone	☐ Ceramic/Baked c	lay	☐ Paper/Cardboard			☐ Packaging		
	☐ Automotive ☐ Cosmetics	□ Graphics □ Bottling		☐ Pharmace☐ Other sec		□ Food			
2)	With what material is the p	product to be handled made?							
	☐ Plastic ☐ Steel sheet	□ Glass □ Marble/Granite		□ Wood □ Rubber			aper/Cardboard ther		
3)	What is the surface of the	product to be gripped like?							
	□ Dry □ Corrugated	□ Wet □ Flaky	☐ Smooth ☐ Porous		□ Rough □ Textured		☐ Creased ☐ Bush-hammered		
4)	On the gripping surface the	ere may be impurities such a	s:						
	□ Powder	□ Water	□ Oil		☐ Solvents		□ Other		
5)	What is the temperature of the load to be handled? From°C to +°C □ For a short time °C □ Continuously °C								
6)	What do you need to pick u	-							
	Description of product:		••••••••						
						10			
		A STATE OF THE PARTY OF THE PAR	Billing Billin	SCHOOL STREET					
							□ Other		
				5					



12) In what position will the load to be handled be?

☐ Vertical



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7)	7) What shape is the product to be handled?									
	□ Square □ Irregular			□ Rectangular □ Other		□ Triangular			□ Round	
8)	What are the	dimensions an	d weight of th	e load?						
	☐ Sheet / Block		□ Cyl	☐ Cylinder / Disc		☐ Pallets / Tables		☐ Beams / Tiles		
4	B		H	B		B H1		B D D D D D D D D D D D D D D D D D D D		
	Size	A	В	Н	Н1	С	D	ΔΗ	ΔΑ	Weight
	Minimum	mm	mm	mm	mm	mm	mm	mm	mm	kg
	Maximum	mm	mm	mm	mm	mm	mm	mm	mm	kg
	On what mach	oorphic robot		□ Carte	esian axes poi		☐ Other			
11)	How will the l	oad be handle	d?							
□ Vertically				☐ Horiz	ontally	☐ Both ways				
			NITE NITE				NEW TOTAL STATE OF THE PARTY OF		-	

☐ Horizontal

☐ Inclined



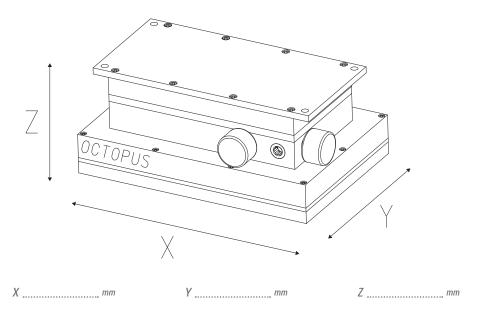
3D drawings are available on vuototecnica.net

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13) Is the position of the load always	ys well defined?	
□ Yes	$\ \square$ No, errors of deviation may occur within:	mr
14) What are the maximum acceler	ation values?	\(\z
☐ Z-axis acceleration m/s² ☐ Y-axis acceleration m/s² ☐ X-axis acceleration m/s²		y
15) How is the product picked up?		x V
☐ From above	☐ From below	\Box From the side
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16) What can the maximum overall dimensions of the Octopus gripping system be, related to your needs?









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17	7) By what device would you l	like to generate the v	acuum?						
	☐ Electrical vacuum pump ☐ Pneumatic vacuum generator								
	If you selected a vacuum pump, indicate the electrical characteristics available:								
	Electrical power:	☐ Single-phase ☐ Three-phase	□ Volt 230 – □ Volt 230/4		□ Other □ Other	VoltVolt		/z/z /z	
	If you selected a pneumatic vacuum generator, indicate the characteristics of the available compressor:								
	☐ Installed power kW								
18	18) Other technical data required:								
	□ Maximum gripping time sec □ Maximum cycle time sec								
19	19) At which height above sea level is the Octopus system to be installed?								
	□ <i>m</i>								
20)) What other components mu	ust be moved in addi	tion to the produc	t?					
	☐ Separators	□ Empty p	allets	☐ Contail	ners		Other	••••••	
	For Boxes, containers, vess	els and similar, supp	ly:						
	☐ Relative drawings	□ Layout		☐ Grippin	ng arrangement		Other	······································	
21) Gripping tests on your sam	ples							
	We can perform tests for go performed.	ripping and handling	on samples of pro	ducts supplied b	y you and can s	send you vided	os/images r	elative to tests	
22	?) Contact								
	☐ Do you wish to be called☐ Are you interested in a v		□ Yes □ Yes	□ No □ No	If yes, what	date/time?			

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